

Homework 7.

Problem 1 – 10 points.

Consider a flat (no torsion,  $\kappa = 0$ ) trajectory in a bending magnet, with constant radius. Assume that there is no electric field ( $\vec{E} = 0$ , energy is constant) and there is no x-y coupling (skew quadrupole components

and longitudinal magnetic field are zero:  $\frac{\partial B_x}{\partial x} = \frac{\partial B_y}{\partial y} = 0$ ;  $B_s = 0$  - this also makes mechanical and

Canonical momenta equal). Assume that there is a quadrupole component allowed in the magnet

$$\frac{\partial B_y}{\partial x} = \frac{\partial B_x}{\partial y} \neq 0$$

The particle's Hamiltonian is then split in two uncoupled parts:  $(y, p_y)$  and  $(x, p_x, \tau, \delta)$

$$\tilde{h} = h_H(x, p_x, \tau, \delta) + h_V(y, p_y) \quad h_H = \frac{p_x^2}{2 \cdot p_o} + F \cdot \frac{x^2}{2} + \frac{\delta^2}{2 \cdot p_o} \cdot \left( \frac{mc}{p_o} \right)^2 + g_x \cdot x \cdot \delta; \quad h_V = \frac{p_y^2}{2 \cdot p_o} + G \cdot \frac{y^2}{2};$$

with (see Lecture 4 formulae (140 and 141))

$$K_1 = -\frac{G}{p_o} = -\frac{e}{p_o c} \frac{\partial B_x}{\partial y}; \quad \frac{F}{p_o} = K^2 + K_1; \quad K \equiv K_o = -\frac{eB_y}{p_o c}; \quad \beta_o = \frac{p_o c}{E_o}; \quad g_x = -\frac{K}{\beta_o}; \quad \frac{mc}{p_o} = \frac{1}{\gamma_o \beta_o};$$

where I introduced  $K_o$  and  $K_1$  notions frequently used in accelerator literature. Because  $p_o$  is constant, I would recommend you switch to switch to dimensionless momenta

$$p_{x,y} \rightarrow \frac{p_{x,y}}{p_o}; \quad \delta \rightarrow \frac{\delta}{p_o};$$

$$h_H = \frac{p_x^2}{2} + (K_o^2 + K_1) \cdot \frac{x^2}{2} + \frac{\delta^2}{2 \cdot (\gamma_o \beta_o)^2} - \frac{K_o}{\beta_o} \cdot x \cdot \delta; \quad h_V = \frac{p_y^2}{2} - K_1 \cdot \frac{y^2}{2};$$

Since vertical motion is completely separated from that horizontal plane, there is a little incentive to use 6x6 matrices.

3 point. Unless you want to use 6x6 matrices, derive explicit 2x2 matrices for vertical motion without any assumptions about the sign and value of  $K_1$  (i.e. all 3 cases).

7 point. Similarly, derive 4x4 matrices to calculate motion in horizontal plane without any assumptions of the sign and value of  $K_1$  and value of  $\beta_o \neq 0$ . Compare it with expression we derived in Lecture 8.

Hint: Motion in horizontal plane has zero  $\det \mathbf{H}$ .